

MultiV - Unit 1

3D Distance Formula: $d^2 = (x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2$

3D Sphere Formula: $r^2 = (x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2$

Magnitude of a Vector: $|v| = \sqrt{x^2 + y^2}$

Direction of a Vector: $\tan(\theta) = y/x$

Unit Vector in Direction of Other Vector: $u = v / |v|$

Dot Product: $u \cdot v = \langle x_1 x_2 + y_1 y_2 \rangle$

If the dot product of two vectors is 0, the vectors are orthogonal

Magnitude²: $|u|^2 = u \cdot u = x^2 + y^2$

Law of Cosines Math: $u \cdot v = |u| |v| \cos(\theta) \rightarrow \cos(\theta) = (u \cdot v) / |u| |v|$

|Proj_u(v)| = $v \cdot (u / |u|)$

Proj_u(v) = $|\text{proj}_u(v)| \times (u / |u|)$

Matrices: $\begin{vmatrix} a & c \\ x & x \end{vmatrix} = |e|$
 $\begin{vmatrix} b & d \\ y & y \end{vmatrix} = |f|$

Inverse Matrices: $A \times A^{-1} = I$

Determinant: $ad-bc$ (area of parallelogram)

If A^{-1} exists, $\det A \neq 0$

Cross Product: $u \times v = \begin{vmatrix} i & j & k \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix} i - \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix} j + \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} k$

Finding Parametric Equations from Two Points:

- 1) Set up vertical vectors on left side of = with x, y, and possibly z variables
- 2) Use first point as first vertical vector on right side of =
- 3) Find vector between two points, multiply by t for final part of vector equation
- 4) Vertically separate to get parametric equations by variable

Find Distance from a Point to a Line:

- 1) Find equation of line
- 2) Find vector from line to point using a random point on the line
- 3) Project the vector you found from point to line onto the line
 - If given parametric form of line, use the given start point and then the number attached to t is the actual vector of the line
- 4) Find the rejection, which is the shortest vector from the line to the point
 - Rejection = (vector from line to point) - (projection of vector onto line)
- 5) The magnitude of the rejection vector is the distance from the line to the point

Equation of Plane: $ax + by + cz = d$

Position of Point r on Plane: $n \cdot (r - p) = 0$

- n (normal) represented in equation by vertical (a, b, c)
- p (given point) represented by actual values
- r (point we are finding) represented by vertical (x, y, z)

Scalar Form of Point on Plane: $a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$

Finding Equation of a Plane from Three Points:

- 1) Given the three points, find two vectors between the points
- 2) Find the cross product of these two vectors
 - This new vector is n (normal), perpendicular to the plane we are finding
- 3) Pick a random point that we know for sure is on the plane
 - Good idea is to use one of the starting given points
- 4) Use the equation $n \cdot (r - p) = 0$ with (a, b, c) as r values \rightarrow solve for standard form of plane

Find Distance from Plane to Origin (or any point):

- 1) Take the coefficients from the equation of the plane to create the normal vector
- 2) Find a point on the plane by setting y and z equal to 0, solve for equation
- 3) Find vector between given point and random point on plane
- 4) Project this vector onto the normal

Going from Rectangular (x, y, z) to Cylindrical (r, theta, z):

- 1) Solve for r with the equation $r^2 = x^2 + y^2$
- 2) Find θ by $\tan(\theta) = y/x$

Going from Cylindrical (r, theta, z) to Spherical (rho, theta, phi):

- 1) Find ρ by $r^2 + z^2 = \rho^2$
- 2) Find ϕ by $z = \rho \cos(\phi)$